

Cansat Leader  
**CLTP**  
Training Program



CanSat Leader Training  
Program (CLTP) - 8<sup>th</sup> Cycle

# Final Presentation

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**日本大学**  
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# Mission Statement

## **Estimating Impact-Force of a Re-entry Vehicle For Hazardous Analysis and Structure improving**

# Mission success

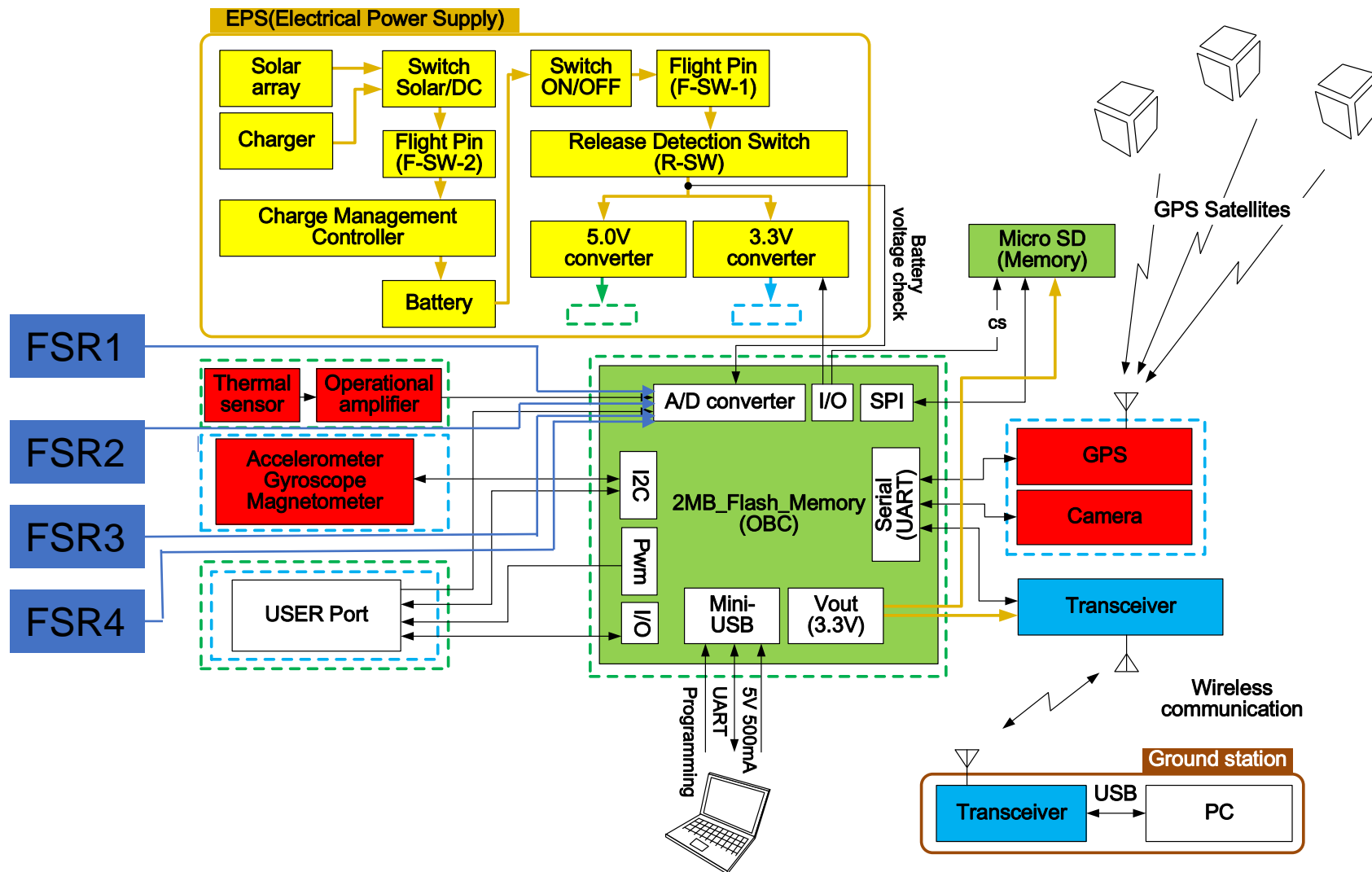
- 9 axis sensor running and saving measurements to SD+ Temp +volt. **Minimum Success**
- 9 axis sensor running and transmitting measurements to ground station+Temp +volt **Success mission**
- Measuring impact force **Extra-Success**

# Mission Requirements

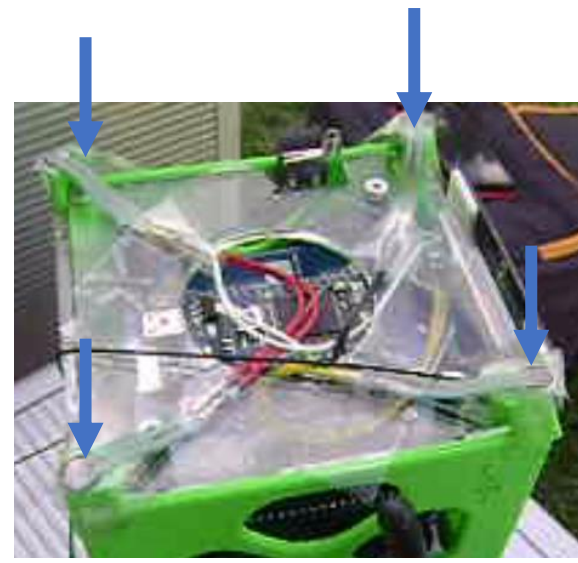
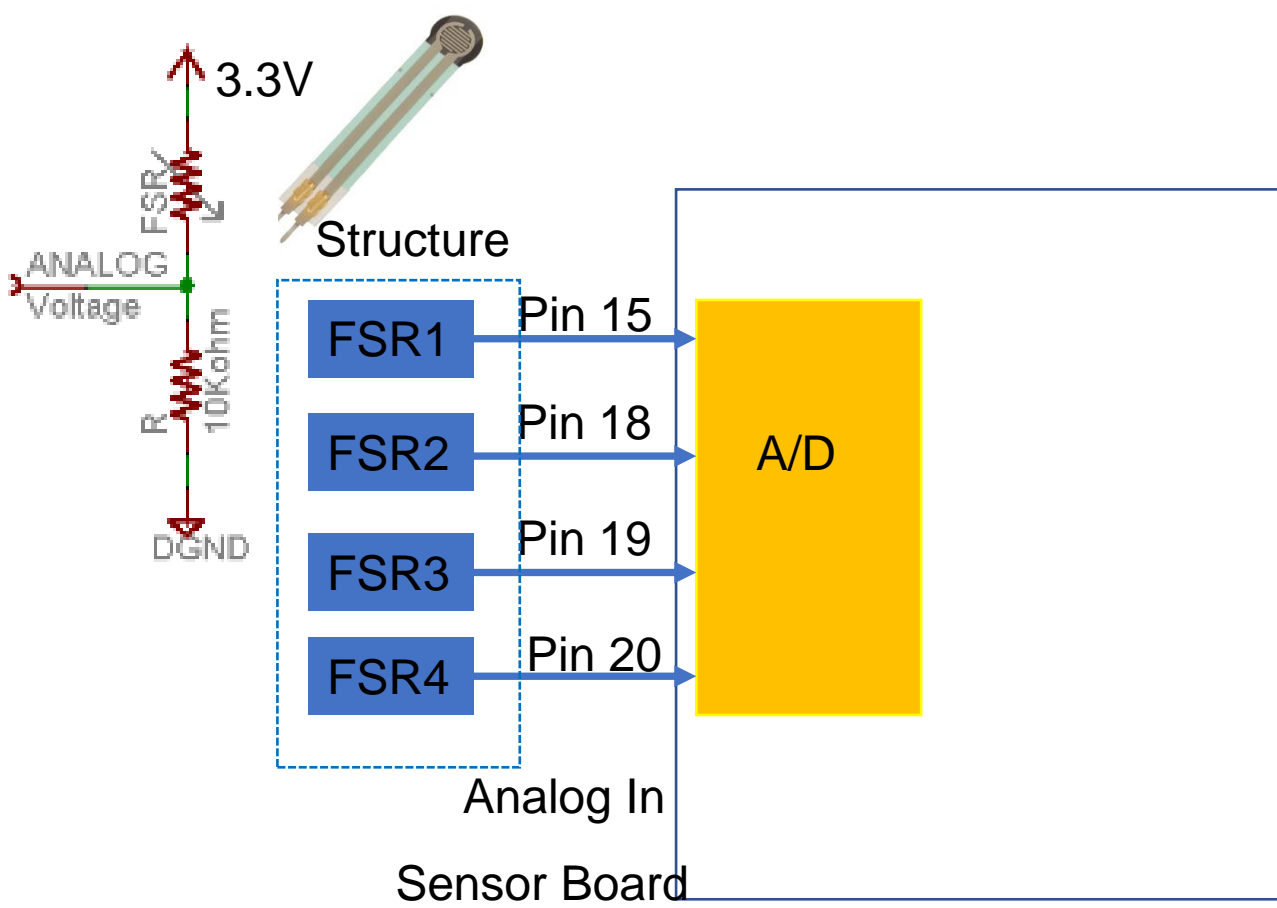
No.	Event	Requirement	Required Function	Verification Way
R-1	Preparation Phase	All systems having power	Check leds	All lights on
R-2		Wire are in place	Check wires	All wires are in place
R-3	Standby time phase	Battery Voltage is >4 volt	To charge battery from the external source	Confirm battery is charged using Multi-meter
R-4	Launch Phase	Install satellite on octocopter	Installation	Visual inspection
R-5		Launch	Run the octocopter	
R-6	Mission Phase	Release from octocopter		Visual inspection
R-7		Open parachute	Release command	
R-8		Getting the required data	Receiving data at Ground station	Data shows on Ground station
R-9		Landing	Manual landing of octocopter	Visual inspection
R-10	Analysis Phase	Structure checking and hazardous analysis	Structure analysis for structure and for human head	Results are consistent with scientific findings

**ALL OK**

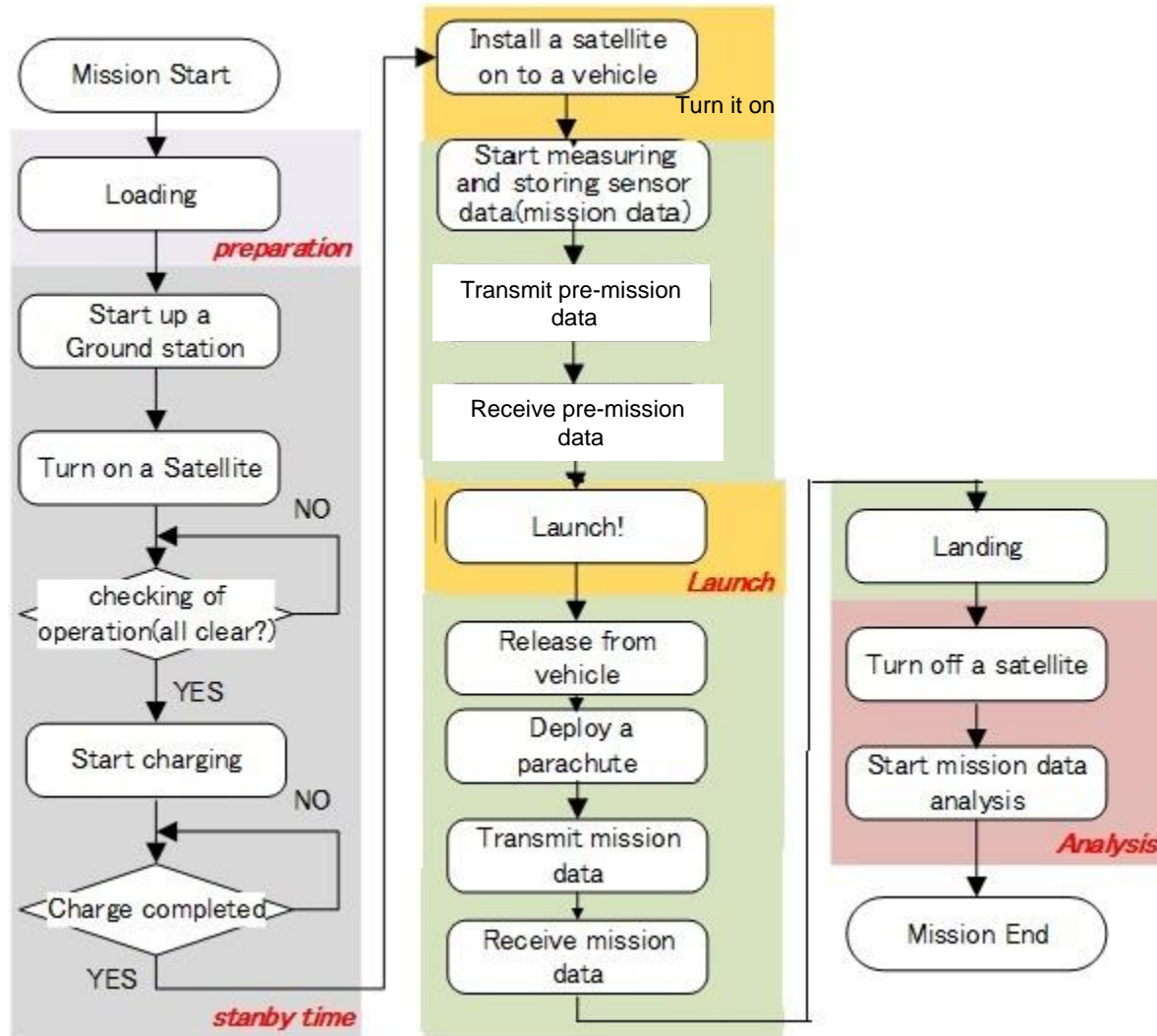
# Satellite System Architecture



# Payload Subsystem Architecture



# Mission Sequence





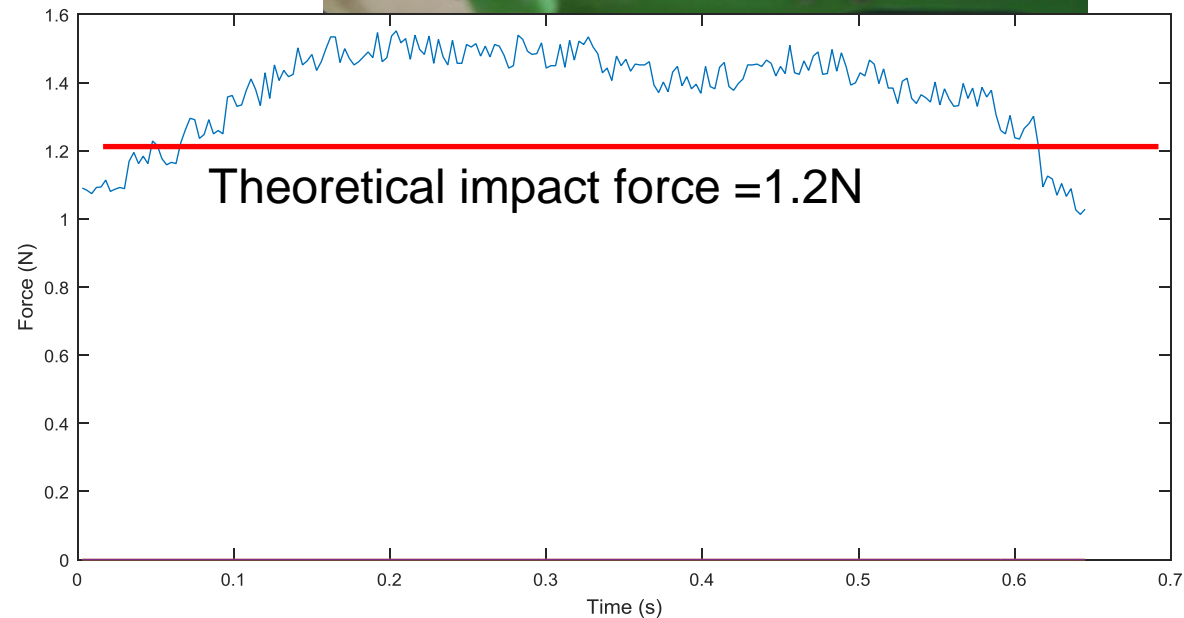
# Validation and Verification Plan/Testing

## (1) Payload

The satellite were dropped from a 50 cm height and data were recorded.



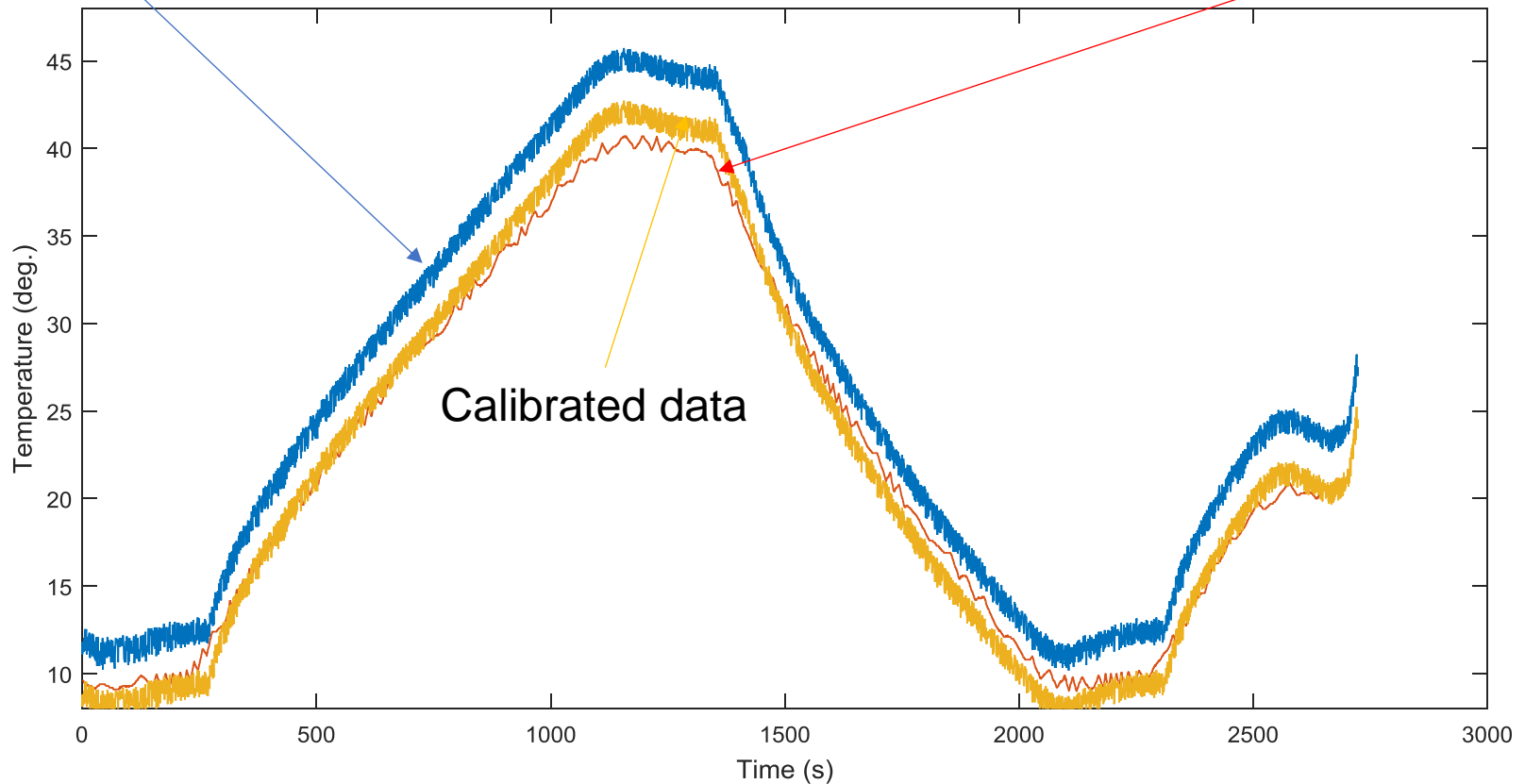
The load shows on one leg only and by inspection of satellite this leg was broken due to higher stress.



# Validation and Verification Plan/Testing

HEPTA sat Thermal sensor

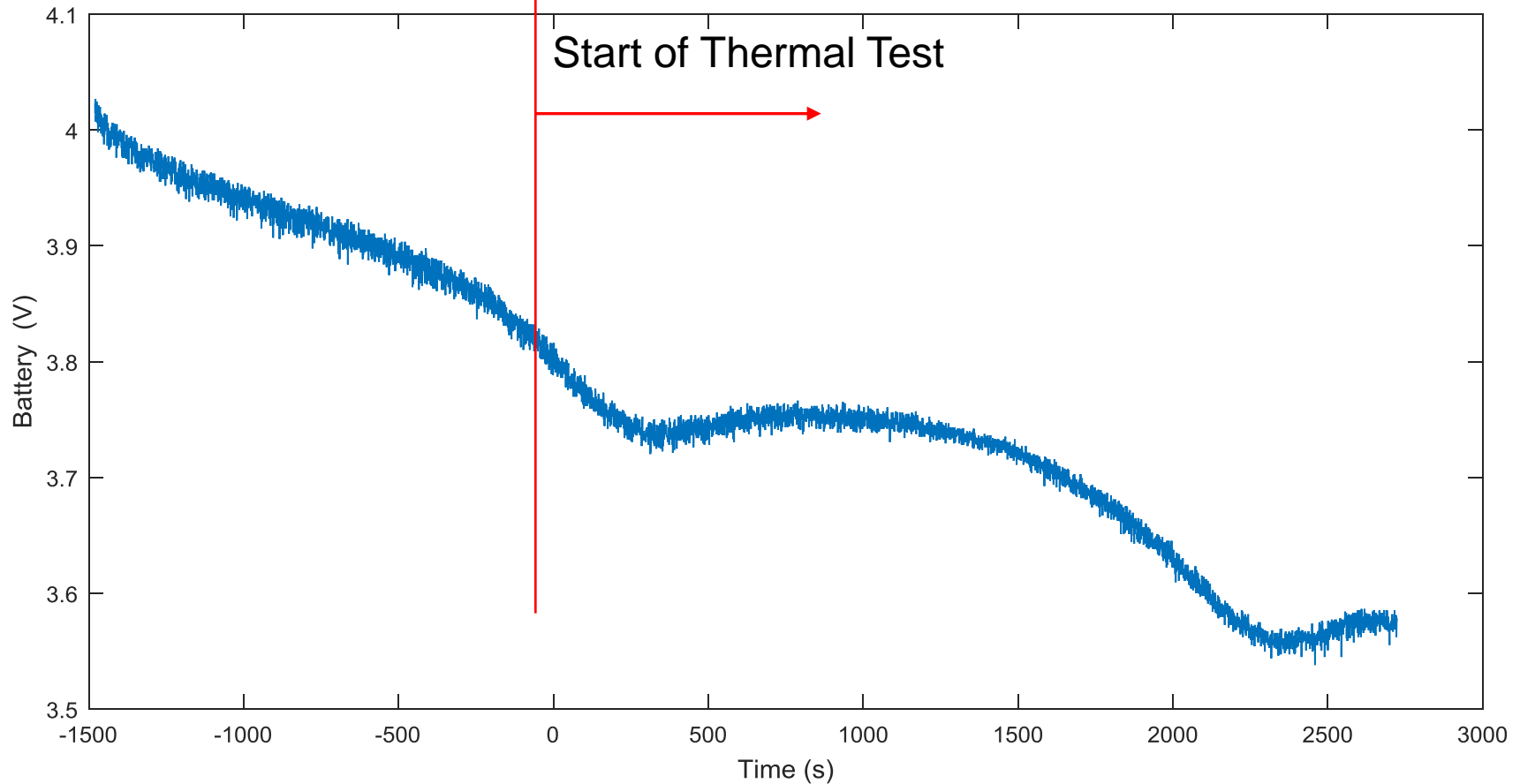
Thermal Chamber



## (2) Thermal sensor calibration

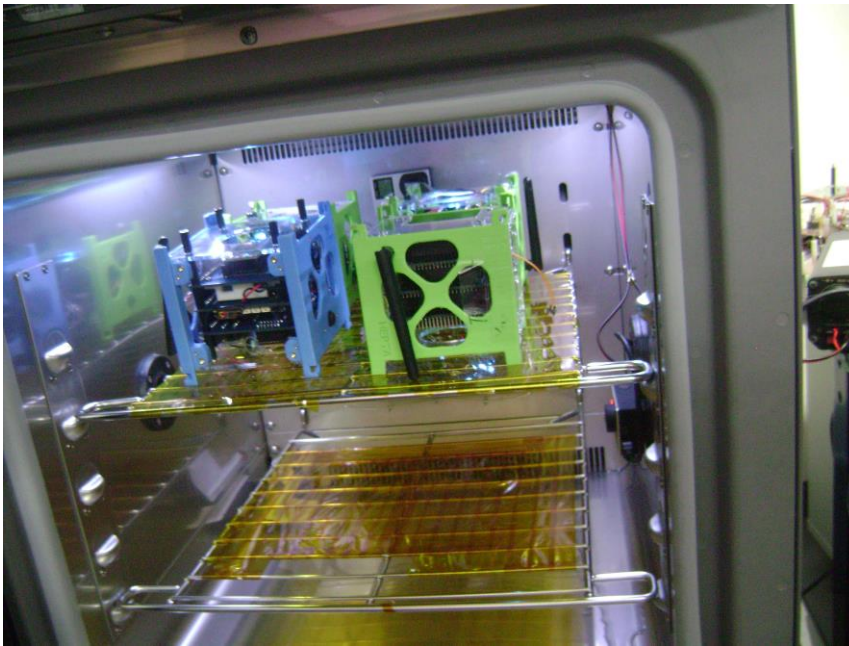
# Validation and Verification Plan/Testing

## (3) Battery Endurance Check

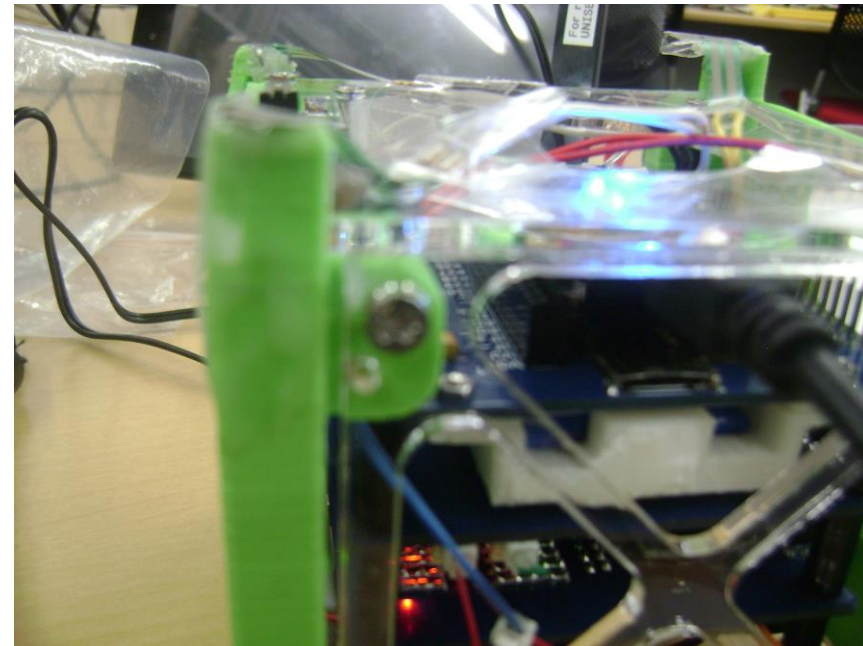


# Validation and Verification Plan/Testing

## (4) Communications with Xbee and data storage on the CD



Thermal Test



Drop Test

# Flight Result: First Attempt

- 9 axis sensor running and saving measurements to SD. **Minimum Success** ✓
- 9 axis sensor running and transmitting measurements to ground station (seems slower than expected).  
**Success mission** ✓
- No forces were recorded for the four FSR sensors.  
**Extra-Success mission !! need to wait for analysis**

## Flight Result: Second Attempt

- 9 axis sensor running and saving measurements to SD. **Minimum Success** ✓
- 9 axis sensor running and transmitting measurements to ground station (seems slower than expected – suspecting interference). **Success mission** ✓
- No forces were recorded for the four FSR sensors.  
**Extra-Success mission !! (need to wait for analysis)**

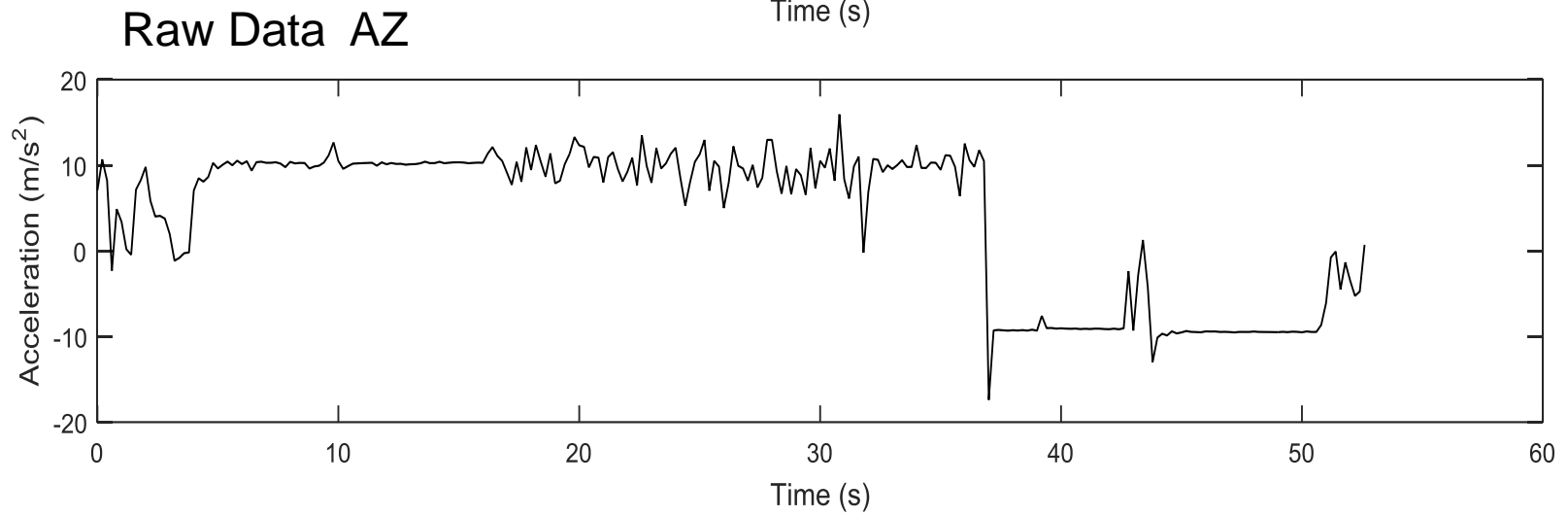
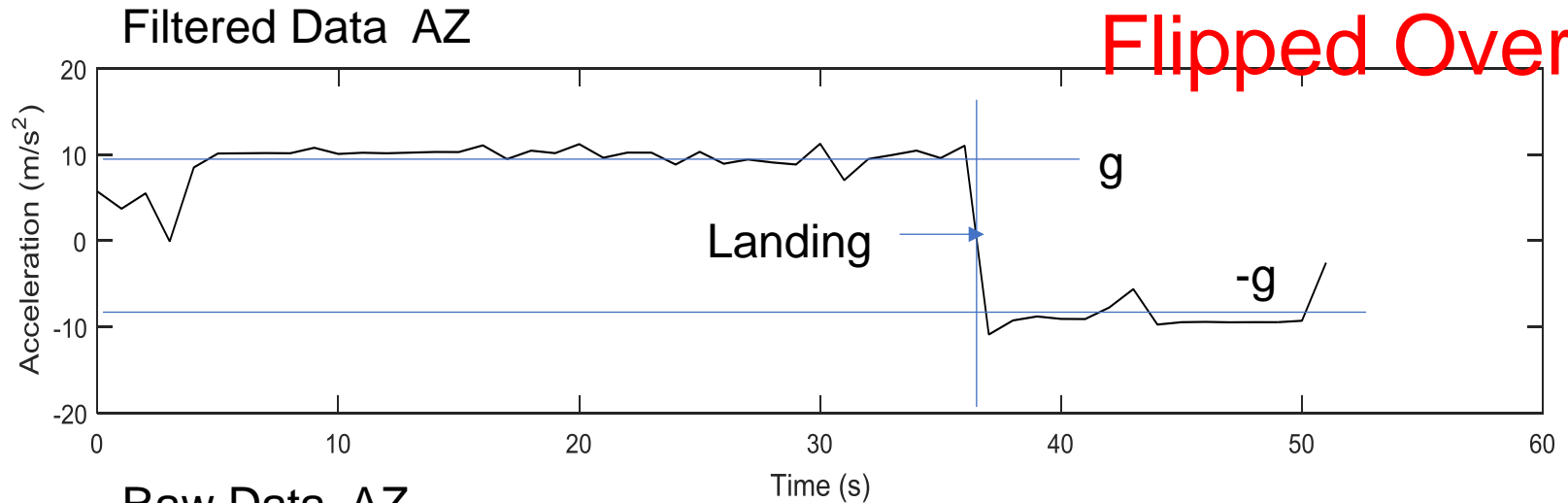
# Flight Result: Third Attempt

- Keeping away from octocopter remote control.
- 9 axis sensor running and saving measurements to SD. **Minimum Success** ✓
- 9 axis sensor running and transmitting measurements to ground station. **Success mission** ✓
- No forces were recorded for the four FSR sensors.

**Extra-Success mission !! need to wait for analysis**

# Analyzing Results (Test 1,2)

Satellite  
Flipped Over !

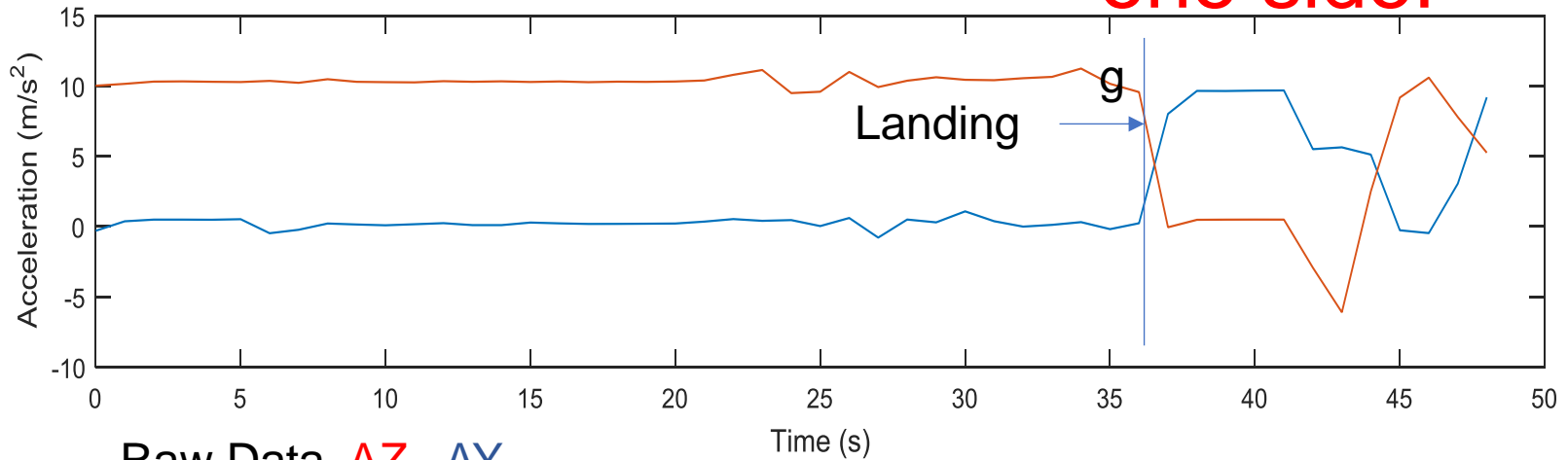




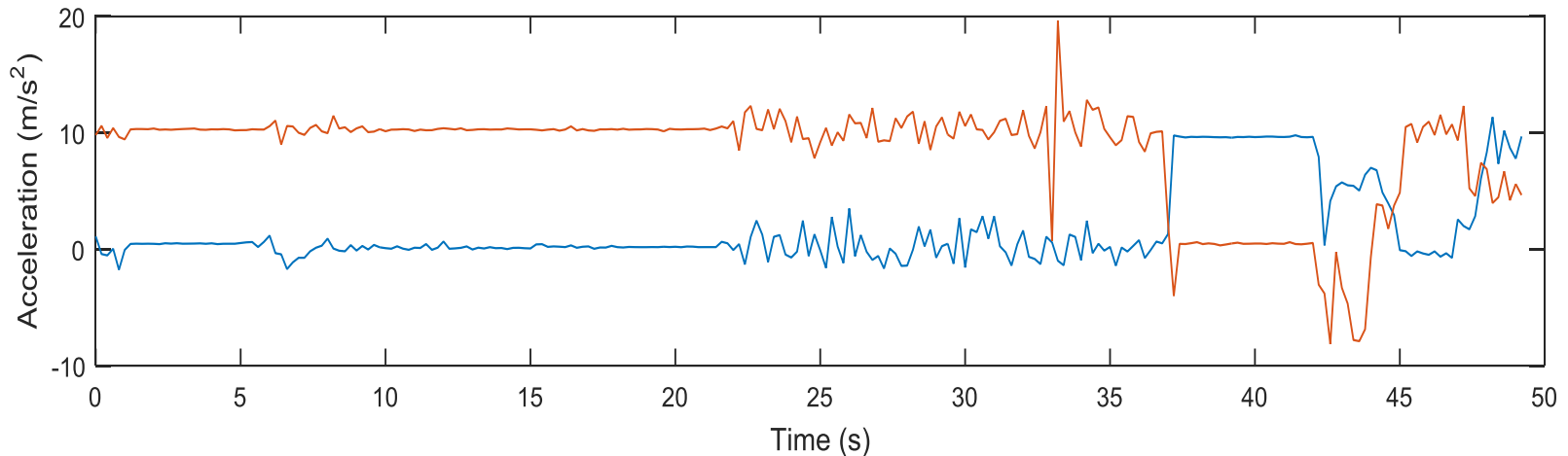
# Analyzing Results (Test 3)

Satellite Fall on one side!

Filtered Data **AZ**, **AY**



Raw Data **AZ**, **AY**



# Controlled drop on Grass

I did several drops on the grass from random altitude and could get one reading each drop ranging from 400gf to 1500gf (4-15N)



# Conclusions

- FSR are working fine for calculating impact forces under controlled experiment (drop test).
- In real flight nothing can guaranty that the satellite will land on its
- legs.
- Impact force can break
- the leg of the satellite.



# Recommendation and Future Work (Mission)

- For FSR to work in general flight test, we need more on all sides of the satellites.
- I would like to model the satellite and the parachute motion dynamics.
- I would like to try different experiments and sensors

# Feedback and Recommendation (CLTP)

- Structure of the Hepta need improvement (strengthening the legs and parachute connections.
- A day or two more for the training period will be appreciated.



Thank  
you

*For a great  
opportunity*