CLTP Presentation

2014 September 8th

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Introduction

* Education

- 1992 ~ 1996 : Korea University, Bachelor degree for the control engineering
- * 1996 ~ 1998 : Korea University, Master degree for the electrical engineering
- * 2006 ~ 2009: University of Tokyo, PhD of the engineering of Aeronautics and Astronautics

* Career

- * 1998 ~ 2005 : Hyundai Motor Group
- * 2009 ~ 2014 : Axelspace Corporation

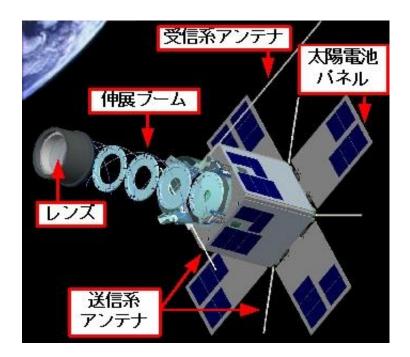
(2006 ~ 2009)

- * CanSat program
 - * UAV of wing-body craft



 $(2006 \sim 2009)$

- * PRISM
 - * NAC (Narrow Angle Camera) System
 - * WAC (Wide Angle Camera) System



 $(2009 \sim 2014)$

* WNISAT-1

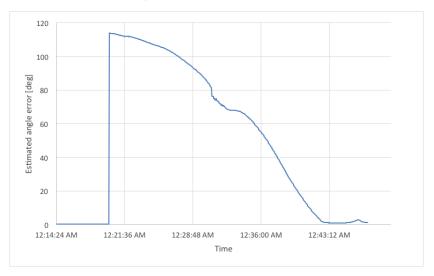
- * 10kg mass
- * Camera mission
- Laser mission for CO₂ check
- Launched at November/2013
- Commissioning operation is over at July/2014







- * Attitude Determination and Control System
 - Simulation on Matlab/Simulink
 - Control structure and algorithm
 - * Coding on Linux using C++
 - * Success on 3 axes control (June/2014)



- * AIT(Assembly Integration and Test)
- * Main Operator (November/2013 ~ July/2014)





- * Magnetic device
 - Magnetic sensor using magnetic resistor device
 - * Magnetic torquer
 - * Management of residual magnetic moment



- * Star sensor
 - * Star identification algorithm
 - * Assembly
 - Environmental test / Night sky view test
 - * Optical calibration
 - * Alignment work



Expectation for CLTP5

* Good chance for the general knowledge of the small satellite

* Valuable event of CanSat Kit

* Sharing experience with many people